



Faculty Of Engineering & Architecture

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linear system of equation (Jacobi method)

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## Iterative method of solving linear system of equation

These methods solves the problem

$$Ax = b$$

Indirectly they generate a sequence of vectors  $\underline{x}_k$ , starting with any initial guess  $\underline{x}_0$ , hopefully converging to the solve  $\underline{x}$ . ( $\underline{x}_0, \underline{x}_1, \underline{x}_2, \dots$ )

### General description

$\underline{x}$  Solves,  $A\underline{x} = \underline{b}$  if and only if it solves

$$\underline{0} = \underline{b} - A\underline{x}$$

If and only if it solves:

$$C \underline{x} = C \underline{x} + \underline{b} - A \underline{x}$$

Where C is a non – singular matrix

If and only if it solves

$$\underline{x} = C^{-1} \underline{b} + C^{-1} (C - A) \underline{x}$$

To concludes:

$\underline{x}$  is a solution to

$$A \underline{x} = \underline{b} \tag{1}$$

If and only if it is a solution to

$$\underline{x} = \underline{d} + T \underline{x} \tag{2}$$

Where  $\underline{d} = C^{-1} \underline{b}$  ,  $T = C^{-1} (C - A)$

Now, starting with any initial guess  $\underline{x}_0$  and using equation (2) the following

sequence is constructed

$$\underline{x}_{k+1} = \underline{d} + T \underline{x}_k \quad (3) \quad k= 0, 1, 2,$$

.....

## Jacobi method

### A-Using matrix

It is an iterative method, defined by equation (3) for which

$$C = \begin{bmatrix} a_{11} & 0 & \dots & 0 \\ 0 & a_{22} & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & a_{nn} \end{bmatrix}$$

For C to be non-singular  $a_{ii}$  must not be zero for any i

$$C^{-1} = \begin{bmatrix} \frac{1}{a_{11}} & 0 & \dots & 0 \\ 0 & \frac{1}{a_{22}} & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & \frac{1}{a_{nn}} \end{bmatrix}$$

$$\underline{d} = C^{-1} \underline{b} = \begin{bmatrix} \frac{1}{a_{11}} & 0 & \dots & 0 \\ 0 & \frac{1}{a_{22}} & \dots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & \dots & 0 & \frac{1}{a_{nn}} \end{bmatrix} \begin{bmatrix} b_1 \\ \vdots \\ b_j \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} \frac{b_1}{a_{11}} \\ \vdots \\ \frac{b_j}{a_j} \\ \vdots \\ \frac{b_n}{a_{nn}} \end{bmatrix}$$

$$T = C^{-1}(C - A) = C^{-1} \begin{bmatrix} 0 & -a_{12} & \dots & \dots & -a_{1,n} \\ -a_{21} & 0 & -a_{23} & & -a_{2,n} \\ \vdots & & 0 & & \vdots \\ \vdots & & & \ddots & \vdots \\ \vdots & & & & \vdots \\ -a_{n1} & \dots & \dots & \dots & -a_{n,n-1} & 0 \end{bmatrix}$$

$$T = \begin{bmatrix} 0 & \frac{-a_{12}}{a_{11}} & \dots & \dots & \frac{-a_{1,n}}{a_{11}} \\ \frac{-a_{21}}{a_{22}} & 0 & \frac{-a_{23}}{a_{22}} & & \frac{-a_{2,n}}{a_{22}} \\ \vdots & & \vdots & & \vdots \\ \vdots & & & \ddots & \vdots \\ \vdots & & & & \vdots \\ \frac{-a_{n1}}{a_{nn}} & \dots & \dots & \dots & \frac{-a_{n,n-1}}{a_{nn}} & 0 \end{bmatrix}$$

That is

$$t_{ij} = \begin{cases} 0 & i = j \\ -\frac{a_{ij}}{a_{ii}} & i \neq j \end{cases}$$

Now if  $(\underline{x}_{k+1})_i$  is the  $i$ th component of  $\underline{x}_{k+1}$

Then

$$(\underline{x}_{k+1})_i = \underline{d}_i + (T \underline{x}_k)_i$$

Where  $(T \underline{x}_k)_i$  is the  $i$ th component of  $T \underline{x}_k$

$$\underline{d}_i = \frac{b_i}{a_{ii}}$$

$$(T \underline{x}_k)_i = [t_{i1} \quad t_{i2} \quad \dots \quad t_{in}]$$

$$= \sum_{j=1}^n t_{ij} (x_k)_j$$

$$= \sum_{j=1}^n -\frac{a_{ij}}{a_{ii}} (x_k)_j$$

$$= -\frac{1}{a_{jj}} \left[ \sum_{j=1}^{j-1} a_{jy} (\underline{x}_k)_j + \sum_{j=i+1}^n a_{jy} (\underline{x}_k)_j \right]$$

$$(\underline{x}_{k+1})_j = \frac{1}{a_{jj}} \left[ b_j - \sum_{j=1}^{j-1} a_{jy} (\underline{x}_k)_j - \sum_{j=i+1}^n a_{jy} (\underline{x}_k)_j \right]$$

## Example

$$A = \begin{bmatrix} 4 & 1 & 1 \\ 1 & 4 & 1 \\ 1 & 1 & 4 \end{bmatrix}, \quad b = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \underline{x}_0 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$(\underline{x}_1)_j = \frac{1}{a_{jj}} \left[ b_j - \sum_{j=1}^{j-1} a_{jy} (\underline{x}_0)_j - \sum_{j=i+1}^3 a_{jy} (\underline{x}_0)_j \right]$$

$$j=1$$



$$(\underline{x}_1)_1 = \frac{1}{a_{11}} \left[ b_1 - \sum_{j=1}^{j-1} a_{1j} (\underline{x}_0)_j - \sum_{j=i+1}^3 a_{1j} (\underline{x}_0)_j \right]$$

$$(\underline{x}_1)_1 = \frac{1}{4} [1 - 1(\underline{x}_0)_2 - 1(\underline{x}_0)_3] = \frac{1}{4} [1 - 0 - 0] = \frac{1}{4}$$

$$(\underline{x}_1)_2 = \frac{1}{4} [1 - 1(\underline{x}_0)_1 - 1(\underline{x}_0)_3] = \frac{1}{4} [1 - 1 - 0] = 0$$

$$(\underline{x}_1)_3 = \frac{1}{4} [1 - 1(\underline{x}_0)_1 - 1(\underline{x}_0)_2] = \frac{1}{4} [1 - 1 - 0] = 0$$

$$\underline{x}_1 = \begin{bmatrix} 1 \\ 4 \\ 0 \\ 0 \end{bmatrix}$$

## B-Using equation

## Example

$$a_{11} x_1 + a_{12} x_2 + a_{13} x_3 = b_1$$

$$a_{21} x_1 + a_{22} x_2 + a_{23} x_3 = b_2$$

$$a_{31} x_1 + a_{32} x_2 + a_{33} x_3 = b_3$$

Rewrite the equations, solving for the unknown

$$x_1 = \frac{1}{a_{11}} [b_1 - a_{12} x_2 - a_{13} x_3]$$

$$x_2 = \frac{1}{a_{22}} [b_2 - a_{21} x_1 - a_{23} x_3]$$

$$x_3 = \frac{1}{a_{33}} [b_3 - a_{31} x_1 - a_{32} x_2]$$

Then, iterate as in fixed point iteration, starting with an initial guess

$$x_1^{(k+1)} = \frac{1}{a_{11}} [b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)}]$$

$$x_2^{(k+1)} = \frac{1}{a_{22}} [b_2 - a_{21}x_1^{(k)} - a_{23}x_3^{(k)}]$$

$$x_3^{(k+1)} = \frac{1}{a_{33}} [b_3 - a_{31}x_1^{(k)} - a_{32}x_2^{(k)}]$$

Stop until the condition verify

$$|x_i^{(k+1)} - x_i^{(k)}| \leq \varepsilon$$

Where:  $\varepsilon$  = given tolerance

**Example:**

Apply the Jacobi method to the system  
 $3u+v=5$ ,  $u+2v=5$

## Solution:

Begin by solving the first equation for  $u$  and the second equation for  $v$ . we will use the initial guess  $(u_0, v_0) = (0, 0)$ . We have

$$u = \frac{5-v}{3} \quad , \quad v = \frac{5-u}{2}$$

The two equations are iterated

$$\begin{bmatrix} u_0 \\ v_0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} u_1 \\ v_1 \end{bmatrix} = \begin{bmatrix} \frac{5-v_0}{3} \\ \frac{5-u_0}{2} \end{bmatrix} = \begin{bmatrix} \frac{5-0}{3} \\ \frac{5-0}{2} \end{bmatrix} = \begin{bmatrix} \frac{5}{3} \\ \frac{5}{2} \end{bmatrix}$$

$$\begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{5-v_1}{3} \\ \frac{5-u_1}{2} \end{bmatrix} = \begin{bmatrix} \frac{5-5/2}{3} \\ \frac{5-5/3}{2} \end{bmatrix} = \begin{bmatrix} \frac{5}{6} \\ \frac{5}{3} \end{bmatrix}$$

$$\begin{bmatrix} u_3 \\ v_3 \end{bmatrix} = \begin{bmatrix} \frac{5-v_2}{3} \\ \frac{5-u_2}{2} \end{bmatrix} = \begin{bmatrix} \frac{5-5/3}{3} \\ \frac{5-5/6}{2} \end{bmatrix} = \begin{bmatrix} \frac{10}{9} \\ \frac{25}{12} \end{bmatrix}$$

Further steps of Jacobi show convergence toward the solution, which is [1,2]

The algorithm of Jacobi method

- Read(n,A,b)
- Read(x,e)

- Repeat
- For  $i=1$  to  $n$  do
- $Y_i = b_i$
- For  $j=1$  to  $i-1$  do
- $Y_i = y_i - a_{ij} * x_j$
- $Y_i = y_i / a_{ii}$
- $Diff = y - x$
- For  $i=1$  to  $n$  do
- $X_i = y_i$
- Until ( $diff < e$ )